■ 미전교

1) 합성 전

< BEFORE COMPOSITE SELF-WEIGHT LOAD >

SYSTEM
LENGTH=M FORCE=kN

JOINT
1 X= 0.000 Y=0.000 Z=0.000
2 X= 4.450 Y=0.000 Z=0.000
3 X= 9.450 Y=0.000 Z=0.000
4 X= 14.450 Y=0.000 Z=0.000
5 X= 19.450 Y=0.000 Z=0.000
6 X= 24.450 Y=0.000 Z=0.000
7 X= 29.450 Y=0.000 Z=0.000
8 X= 34.450 Y=0.000 Z=0.000
9 X= 39.450 Y=0.000 Z=0.000
10 X= 44.450 Y=0.000 Z=0.000
11 X= 49.450 Y=0.000 Z=0.000
12 X= 54.450 Y=0.000 Z=0.000
13 X= 59.450 Y=0.000 Z=0.000
14 X= 64.450 Y=0.000 Z=0.000
15 X= 69.450 Y=0.000 Z=0.000
16 X= 74.450 Y=0.000 Z=0.000
17 X= 79.450 Y=0.000 Z=0.000
18 X= 84.450 Y=0.000 Z=0.000
19 X= 89.450 Y=0.000 Z=0.000
20 X= 94.450 Y=0.000 Z=0.000
21 X= 99.450 Y=0.000 Z=0.000
22 X= 104.030 Y=0.000 Z=0.000
23 X= 0.000 Y=-7.700 Z=-0.154
24 X= 4.450 Y=-7.700 Z=-0.154
25 X= 9.450 Y=-7.700 Z=-0.154
26 X= 14.450 Y=-7.700 Z=-0.154
27 X= 19.450 Y=-7.700 Z=-0.154
28 X= 24.450 Y=-7.700 Z=-0.154
29 X= 29.450 Y=-7.700 Z=-0.154
30 X= 34.450 Y=-7.700 Z=-0.154
31 X= 39.450 Y=-7.700 Z=-0.154
32 X= 44.450 Y=-7.700 Z=-0.154
33 X= 49.450 Y=-7.700 Z=-0.154
34 X= 54.450 Y=-7.700 Z=-0.154
35 X= 59.450 Y=-7.700 Z=-0.154
36 X= 64.450 Y=-7.700 Z=-0.154
37 X= 69.450 Y=-7.700 Z=-0.154
38 X= 74.450 Y=-7.700 Z=-0.154
39 X= 79.450 Y=-7.700 Z=-0.154
40 X= 84.450 Y=-7.700 Z=-0.154
41 X= 89.450 Y=-7.700 Z=-0.154
42 X= 94.450 Y=-7.700 Z=-0.154
43 X= 99.450 Y=-7.700 Z=-0.154
44 X= 104.030 Y=-7.700 Z=-0.154
45 X= 0.000 Y=-3.850 Z=-0.077
46 X= 4.450 Y=-3.850 Z=-0.077
47 X= 9.450 Y=-3.850 Z=-0.077
48 X= 14.450 Y=-3.850 Z=-0.077
49 X= 19.450 Y=-3.850 Z=-0.077
50 X= 24.450 Y=-3.850 Z=-0.077
51 X= 29.450 Y=-3.850 Z=-0.077
52 X= 34.450 Y=-3.850 Z=-0.077
53 X= 39.450 Y=-3.850 Z=-0.077
54 X= 44.450 Y=-3.850 Z=-0.077
55 X= 49.450 Y=-3.850 Z=-0.077
56 X= 54.450 Y=-3.850 Z=-0.077
57 X= 59.450 Y=-3.850 Z=-0.077
58 X= 64.450 Y=-3.850 Z=-0.077
59 X= 69.450 Y=-3.850 Z=-0.077
60 X= 74.450 Y=-3.850 Z=-0.077
61 X= 79.450 Y=-3.850 Z=-0.077
62 X= 84.450 Y=-3.850 Z=-0.077
63 X= 89.450 Y=-3.850 Z=-0.077
64 X= 94.450 Y=-3.850 Z=-0.077

65 X= 99.450 Y=-3.850 Z=-0.077
66 X= 104.030 Y=-3.850 Z=-0.077
67 X= 0.000 Y=0.000 Z=-1.150
68 X= 0.000 Y=1.050 Z=-1.150
69 X= 0.000 Y=-1.050 Z=-1.150
70 X= 54.450 Y=0.000 Z=-1.250
71 X= 54.450 Y=1.050 Z=-1.250
72 X= 54.450 Y=-1.050 Z=-1.250
73 X= 104.030 Y=0.000 Z=-1.150
74 X= 104.030 Y=1.050 Z=-1.150
75 X= 104.030 Y=-1.050 Z=-1.150
76 X= 0.000 Y=-7.700 Z=-1.304
77 X= 0.000 Y=-6.650 Z=-1.304
78 X= 0.000 Y=-8.750 Z=-1.304
79 X= 54.450 Y=-7.700 Z=-1.404
80 X= 54.450 Y=-6.650 Z=-1.404
81 X= 54.450 Y=-8.750 Z=-1.404
82 X= 104.030 Y=-7.700 Z=-1.304
83 X= 104.030 Y=-6.650 Z=-1.304
84 X= 104.030 Y=-8.750 Z=-1.304

LOCAL
ADD= 68 ANG=0.000
ADD= 69 ANG=0.000
ADD= 71 ANG=0.000
ADD= 72 ANG=0.000
ADD= 74 ANG=0.000
ADD= 75 ANG=0.000
ADD= 77 ANG=5.872
ADD= 78 ANG=8.049
ADD= 80 ANG=0.000
ADD= 81 ANG=0.000
ADD= 83 ANG=-6.444
ADD= 84 ANG=-8.828

RESTRAINT
ADD= 68 DOF= U2, U3,
ADD= 69 DOF= U2, U3,
ADD= 71 DOF= U1, U2, U3,
ADD= 72 DOF= U1, U2, U3,
ADD= 74 DOF= U2, U3,
ADD= 75 DOF= U2, U3,
ADD= 77 DOF= U3,
ADD= 78 DOF= U3,
ADD= 80 DOF= U1, U3,
ADD= 81 DOF= U1, U3,
ADD= 83 DOF= U3,
ADD= 84 DOF= U3,

MATERIAL
Name=1
E=2.05e+008
Name=2
E=2.05e+008
Name=3
E=2.05e+008
Name=4
E=2.05e+008
Name=5
E=2.05e+008
Name=6
E=2.05e+008
Name=7
E=2.05e+008
Name=8
E=2.05e+008
Name=9
E=2.05e+008
Name=10
E=2.05e+008
Name=11
E=2.05e+008
Name=12

E=2.05e+008

FRAME SECTION
Name= 1 Mat= 1 A=0.12720 I=0.12369044, 0.13601208 J=0.15613088 : GIRDER
Name= 2 Mat= 2 A=0.13120 I=0.14852714, 0.14335621 J=0.17727419 : GIRDER
Name= 3 Mat= 3 A=0.14296 I=0.16796144, 0.15182694 J=0.19170092 : GIRDER
Name= 4 Mat= 4 A=0.17824 I=0.22444044, 0.17723912 J=0.23037929 : GIRDER
Name= 5 Mat= 5 A=0.18916 I=0.23758820, 0.18326520 J=0.23037929 : GIRDER
Name= 6 Mat= 6 A=0.16340 I=0.19725926, 0.16568315 J=0.21457718 : GIRDER
Name= 7 Mat= 7 A=0.27160 I=0.35222502, 0.26631451 J=0.34772150 : GIRDER
Name= 8 Mat= 8 A=0.16648 I=0.20555567, 0.17479430 J=0.21946679 : GIRDER
Name= 9 Mat= 9 A=0.15472 I=0.18454863, 0.16029767 J=0.20085843 : GIRDER
Name= 10 Mat= 10 A=0.02880 I=0.01174211, 0.00005426 J=0.00000138 : CROSSBEAM
Name= 11 Mat= 11 A=0.01680 I=0.00169891, 0.00005412 J=0.00000081 : STRINGER
Name= 12 Mat= 12 A=10.00000 I=10.00000000, 10.00000000 J=10.00000000 : SHOE
Name= 13 Type=Nonpr Sec= 1, 2 Elvar=2.1
Name= 14 Type=Nonpr Sec= 2, 1
Name= 15 Type=Nonpr Sec= 2, 3
Name= 16 Type=Nonpr Sec= 3, 4
Name= 17 Type=Nonpr Sec= 4, 5
Name= 18 Type=Nonpr Sec= 5, 6
Name= 19 Type=Nonpr Sec= 6, 7
Name= 20 Type=Nonpr Sec= 6, 8
Name= 21 Type=Nonpr Sec= 7, 6
Name= 22 Type=Nonpr Sec= 8, 9
Name= 23 Type=Nonpr Sec= 9, 2

FRAME
1 J= 1, 2 Sec=13 Local=12 Pldir=+Z,+X NSEG=4
2 J= 2, 3 Sec=15
3 J= 3, 4 Sec=16
4 J= 4, 5 Sec= 4
5 J= 5, 6 Sec= 4
6 J= 6, 7 Sec= 4
7 J= 7, 8 Sec= 4
8 J= 8, 9 Sec=17
9 J= 9, 10 Sec=18
10 J= 10, 11 Sec=19
11 J= 11, 12 Sec= 7
12 J= 12, 13 Sec= 7
13 J= 13, 14 Sec=21
14 J= 14, 15 Sec=20
15 J= 15, 16 Sec= 8
16 J= 16, 17 Sec= 8
17 J= 17, 18 Sec= 8
18 J= 18, 19 Sec= 8
19 J= 19, 20 Sec=22
20 J= 20, 21 Sec=23
21 J= 21, 22 Sec=14
22 J= 23, 24 Sec=13
23 J= 24, 25 Sec=15
24 J= 25, 26 Sec=16
25 J= 26, 27 Sec= 4
26 J= 27, 28 Sec= 4
27 J= 28, 29 Sec= 4
28 J= 29, 30 Sec= 4
29 J= 30, 31 Sec=17
30 J= 31, 32 Sec=18
31 J= 32, 33 Sec=19
32 J= 33, 34 Sec= 7
33 J= 34, 35 Sec= 7
34 J= 35, 36 Sec=21
35 J= 36, 37 Sec=20
36 J= 37, 38 Sec= 8
37 J= 38, 39 Sec= 8
38 J= 39, 40 Sec= 8
39 J= 40, 41 Sec= 8
40 J= 41, 42 Sec=22
41 J= 42, 43 Sec=23
42 J= 43, 44 Sec=14
43 J= 1, 45 Sec=10 IOFF=1.350 JOFF=0.000 RIGID=1.0
44 J= 45, 23 Sec=10 IOFF=0.000 JOFF=1.350 RIGID=1.0
45 J= 2, 46 Sec=10 IOFF=1.350 JOFF=0.000 RIGID=1.0

46 J= 46, 24 Sec=10 IOFF=0.000 JOFF=1.350 RIGID=1.0
47 J= 3, 47 Sec=10 IOFF=1.350 JOFF=0.000 RIGID=1.0
48 J= 47, 25 Sec=10 IOFF=0.000 JOFF=1.350 RIGID=1.0
49 J= 4, 48 Sec=10 IOFF=1.350 JOFF=0.000 RIGID=1.0
50 J= 48, 26 Sec=10 IOFF=0.000 JOFF=1.350 RIGID=1.0
51 J= 5, 49 Sec=10 IOFF=1.350 JOFF=0.000 RIGID=1.0
52 J= 49, 27 Sec=10 IOFF=0.000 JOFF=1.350 RIGID=1.0
53 J= 6, 50 Sec=10 IOFF=1.350 JOFF=0.000 RIGID=1.0
54 J= 50, 28 Sec=10 IOFF=0.000 JOFF=1.350 RIGID=1.0
55 J= 7, 51 Sec=10 IOFF=1.350 JOFF=0.000 RIGID=1.0
56 J= 51, 29 Sec=10 IOFF=0.000 JOFF=1.350 RIGID=1.0
57 J= 8, 52 Sec=10 IOFF=1.350 JOFF=0.000 RIGID=1.0
58 J= 52, 30 Sec=10 IOFF=0.000 JOFF=1.350 RIGID=1.0
59 J= 9, 53 Sec=10 IOFF=1.350 JOFF=0.000 RIGID=1.0
60 J= 53, 31 Sec=10 IOFF=0.000 JOFF=1.350 RIGID=1.0
61 J= 10, 54 Sec=10 IOFF=1.350 JOFF=0.000 RIGID=1.0
62 J= 54, 32 Sec=10 IOFF=0.000 JOFF=1.350 RIGID=1.0
63 J= 11, 55 Sec=10 IOFF=1.350 JOFF=0.000 RIGID=1.0
64 J= 55, 33 Sec=10 IOFF=0.000 JOFF=1.350 RIGID=1.0
65 J= 12, 56 Sec=10 IOFF=1.350 JOFF=0.000 RIGID=1.0
66 J= 56, 34 Sec=10 IOFF=0.000 JOFF=1.350 RIGID=1.0
67 J= 13, 57 Sec=10 IOFF=1.350 JOFF=0.000 RIGID=1.0
68 J= 57, 35 Sec=10 IOFF=0.000 JOFF=1.350 RIGID=1.0
69 J= 14, 58 Sec=10 IOFF=1.350 JOFF=0.000 RIGID=1.0
70 J= 58, 36 Sec=10 IOFF=0.000 JOFF=1.350 RIGID=1.0
71 J= 15, 59 Sec=10 IOFF=1.350 JOFF=0.000 RIGID=1.0
72 J= 59, 37 Sec=10 IOFF=0.000 JOFF=1.350 RIGID=1.0
73 J= 16, 60 Sec=10 IOFF=1.350 JOFF=0.000 RIGID=1.0
74 J= 60, 38 Sec=10 IOFF=0.000 JOFF=1.350 RIGID=1.0
75 J= 17, 61 Sec=10 IOFF=1.350 JOFF=0.000 RIGID=1.0
76 J= 61, 39 Sec=10 IOFF=0.000 JOFF=1.350 RIGID=1.0
77 J= 18, 62 Sec=10 IOFF=1.350 JOFF=0.000 RIGID=1.0
78 J= 62, 40 Sec=10 IOFF=0.000 JOFF=1.350 RIGID=1.0
79 J= 19, 63 Sec=10 IOFF=1.350 JOFF=0.000 RIGID=1.0
80 J= 63, 41 Sec=10 IOFF=0.000 JOFF=1.350 RIGID=1.0
81 J= 20, 64 Sec=10 IOFF=1.350 JOFF=0.000 RIGID=1.0
82 J= 64, 42 Sec=10 IOFF=0.000 JOFF=1.350 RIGID=1.0
83 J= 21, 65 Sec=10 IOFF=1.350 JOFF=0.000 RIGID=1.0
84 J= 65, 43 Sec=10 IOFF=0.000 JOFF=1.350 RIGID=1.0
85 J= 22, 66 Sec=10 IOFF=1.350 JOFF=0.000 RIGID=1.0
86 J= 66, 44 Sec=10 IOFF=0.000 JOFF=1.350 RIGID=1.0
87 J= 45, 46 Sec=11
88 J= 46, 47 Sec=11
89 J= 47, 48 Sec=11
90 J= 48, 49 Sec=11
91 J= 49, 50 Sec=11
92 J= 50, 51 Sec=11
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98 J= 56, 57 Sec=11
99 J= 57, 58 Sec=11
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102 J= 60, 61 Sec=11
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104 J= 62, 63 Sec=11
105 J= 63, 64 Sec=11
106 J= 64, 65 Sec=11
107 J= 65, 66 Sec=11
108 J= 1, 67 Sec=12
109 J= 68, 67 Sec=12
110 J= 69, 67 Sec=12
111 J= 12, 70 Sec=12
112 J= 71, 70 Sec=12
113 J= 72, 70 Sec=12
114 J= 22, 73 Sec=12
115 J= 74, 73 Sec=12
116 J= 75, 73 Sec=12
117 J= 23, 76 Sec=12
118 J= 77, 76 Sec=12

119 J= 78, 76 Sec=12
120 J= 34, 79 Sec=12
121 J= 80, 79 Sec=12
122 J= 81, 79 Sec=12
123 J= 44, 82 Sec=12
124 J= 83, 82 Sec=12
125 J= 84, 82 Sec=12

LOAD
Name=STEEL : STEEL SELF-WEIGHT LOAD
Type=Distributed Span
Add= 1 RD=0.000, 1.000 Uzp=-14.491, -14.947
Add= 2 RD=0.000, 1.000 Uzp=-14.947, -16.286
Add= 3 RD=0.000, 1.000 Uzp=-16.286, -20.306
Add= 4 RD=0.000, 1.000 Uzp=-20.306, -20.306
Add= 5 RD=0.000, 1.000 Uzp=-20.306, -20.306
Add= 6 RD=0.000, 1.000 Uzp=-20.306, -20.306
Add= 7 RD=0.000, 1.000 Uzp=-20.306, -20.306
Add= 8 RD=0.000, 1.000 Uzp=-20.306, -21.550
Add= 9 RD=0.000, 1.000 Uzp=-21.550, -18.615
Add= 10 RD=0.000, 1.000 Uzp=-18.615, -30.941
Add= 11 RD=0.000, 1.000 Uzp=-30.941, -30.941
Add= 12 RD=0.000, 1.000 Uzp=-30.941, -30.941
Add= 13 RD=0.000, 1.000 Uzp=-30.941, -18.615
Add= 14 RD=0.000, 1.000 Uzp=-18.615, -18.966
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Add=107 RD=0.000, 1.000 Uzp=-1.914, -1.914

Name=CONC : SLAB SELF-WEIGHT LOAD
Type=Distributed Span
Add= 1 RD=0.000, 0.449 Uzp=-62.032, -62.032 R1=-5.618, -5.618
Add= 1 RD=0.449, 1.000 Uzp=-34.589, -34.589 R1=-5.021, -5.021
Add= 2 RD=0.000, 1.000 Uzp=-34.589, -34.589 R1=-5.021, -5.021
Add= 3 RD=0.000, 1.000 Uzp=-34.589, -34.589 R1=-5.021, -5.021
Add= 4 RD=0.000, 1.000 Uzp=-34.589, -34.589 R1=-5.021, -5.021
Add= 5 RD=0.000, 1.000 Uzp=-34.589, -34.589 R1=-5.021, -5.021
Add= 6 RD=0.000, 1.000 Uzp=-34.589, -34.589 R1=-5.021, -5.021
Add= 7 RD=0.000, 1.000 Uzp=-34.589, -34.589 R1=-5.021, -5.021
Add= 8 RD=0.000, 1.000 Uzp=-34.589, -34.589 R1=-5.021, -5.021
Add= 9 RD=0.000, 1.000 Uzp=-34.589, -34.589 R1=-5.021, -5.021
Add= 10 RD=0.000, 1.000 Uzp=-34.589, -34.589 R1=-5.021, -5.021
Add= 11 RD=0.000, 1.000 Uzp=-34.589, -34.589 R1=-5.021, -5.021
Add= 12 RD=0.000, 1.000 Uzp=-34.589, -34.589 R1=-5.021, -5.021
Add= 13 RD=0.000, 1.000 Uzp=-34.589, -34.589 R1=-5.021, -5.021
Add= 14 RD=0.000, 1.000 Uzp=-34.589, -34.589 R1=-5.021, -5.021
Add= 15 RD=0.000, 1.000 Uzp=-34.589, -34.589 R1=-5.021, -5.021
Add= 16 RD=0.000, 1.000 Uzp=-34.589, -34.589 R1=-5.021, -5.021
Add= 17 RD=0.000, 1.000 Uzp=-34.589, -34.589 R1=-5.021, -5.021
Add= 18 RD=0.000, 1.000 Uzp=-34.589, -34.589 R1=-5.021, -5.021
Add= 19 RD=0.000, 1.000 Uzp=-34.589, -34.589 R1=-5.021, -5.021
Add= 20 RD=0.000, 1.000 Uzp=-34.589, -34.589 R1=-5.021, -5.021
Add= 21 RD=0.000, 0.563 Uzp=-34.589, -34.589 R1=-5.021, -5.021
Add= 21 RD=0.563, 1.000 Uzp=-62.032, -62.032 R1=-5.618, -5.618
Add= 22 RD=0.000, 0.449 Uzp=-60.394, -60.394 R1=-7.636, -7.636
Add= 22 RD=0.449, 1.000 Uzp=-33.063, -33.063 R1=-3.475, -3.475

Add= 23 RD=0.000, 1.000 Uzp=-33.063, -33.063 R1=-3.475, -3.475
Add= 24 RD=0.000, 1.000 Uzp=-33.063, -33.063 R1=-3.475, -3.475
Add= 25 RD=0.000, 1.000 Uzp=-33.063, -33.063 R1=-3.475, -3.475
Add= 26 RD=0.000, 1.000 Uzp=-33.063, -33.063 R1=-3.475, -3.475
Add= 27 RD=0.000, 1.000 Uzp=-33.063, -33.063 R1=-3.475, -3.475
Add= 28 RD=0.000, 1.000 Uzp=-33.063, -33.063 R1=-3.475, -3.475
Add= 29 RD=0.000, 1.000 Uzp=-33.063, -33.063 R1=-3.475, -3.475
Add= 30 RD=0.000, 1.000 Uzp=-33.063, -33.063 R1=-3.475, -3.475
Add= 31 RD=0.000, 1.000 Uzp=-33.063, -33.063 R1=-3.475, -3.475
Add= 32 RD=0.000, 1.000 Uzp=-33.063, -33.063 R1=-3.475, -3.475
Add= 33 RD=0.000, 1.000 Uzp=-33.063, -33.063 R1=-3.475, -3.475
Add= 34 RD=0.000, 1.000 Uzp=-33.063, -33.063 R1=-3.475, -3.475
Add= 35 RD=0.000, 1.000 Uzp=-33.063, -33.063 R1=-3.475, -3.475
Add= 36 RD=0.000, 1.000 Uzp=-33.063, -33.063 R1=-3.475, -3.475
Add= 37 RD=0.000, 1.000 Uzp=-33.063, -33.063 R1=-3.475, -3.475
Add= 38 RD=0.000, 1.000 Uzp=-33.063, -33.063 R1=-3.475, -3.475
Add= 39 RD=0.000, 1.000 Uzp=-33.063, -33.063 R1=-3.475, -3.475
Add= 40 RD=0.000, 1.000 Uzp=-33.063, -33.063 R1=-3.475, -3.475
Add= 41 RD=0.000, 1.000 Uzp=-33.063, -33.063 R1=-3.475, -3.475
Add= 42 RD=0.000, 0.563 Uzp=-33.063, -33.063 R1=-3.475, -3.475
Add= 42 RD=0.563, 1.000 Uzp=-60.394, -60.394 R1=-7.636, -7.636
Add= 87 RD=0.000, 0.449 Uzp=-29.535, -29.535
Add= 87 RD=0.449, 1.000 Uzp=-12.711, -12.711
Add= 88 RD=0.000, 1.000 Uzp=-12.711, -12.711
Add= 89 RD=0.000, 1.000 Uzp=-12.711, -12.711
Add= 90 RD=0.000, 1.000 Uzp=-12.711, -12.711
Add= 91 RD=0.000, 1.000 Uzp=-12.711, -12.711
Add= 92 RD=0.000, 1.000 Uzp=-12.711, -12.711
Add= 93 RD=0.000, 1.000 Uzp=-12.711, -12.711
Add= 94 RD=0.000, 1.000 Uzp=-12.711, -12.711
Add= 95 RD=0.000, 1.000 Uzp=-12.711, -12.711
Add= 96 RD=0.000, 1.000 Uzp=-12.711, -12.711
Add= 97 RD=0.000, 1.000 Uzp=-12.711, -12.711
Add= 98 RD=0.000, 1.000 Uzp=-12.711, -12.711
Add= 99 RD=0.000, 1.000 Uzp=-12.711, -12.711
Add=100 RD=0.000, 1.000 Uzp=-12.711, -12.711
Add=101 RD=0.000, 1.000 Uzp=-12.711, -12.711
Add=102 RD=0.000, 1.000 Uzp=-12.711, -12.711
Add=103 RD=0.000, 1.000 Uzp=-12.711, -12.711
Add=104 RD=0.000, 1.000 Uzp=-12.711, -12.711
Add=105 RD=0.000, 1.000 Uzp=-12.711, -12.711
Add=106 RD=0.000, 1.000 Uzp=-12.711, -12.711
Add=107 RD=0.000, 0.563 Uzp=-12.711, -12.711
Add=107 RD=0.563, 1.000 Uzp=-29.535, -29.535

Name=CR-HUNCH : CROSSBEAM HUNCH SELF-WEIGHT LOAD
Type=Distributed Span
Add= 45 RD=0.351, 0.948 Uzp=-0.653, -0.653
Add= 46 RD=0.052, 0.649 Uzp=-1.124, -1.124
Add= 47 RD=0.351, 0.948 Uzp=-0.653, -0.653
Add= 48 RD=0.052, 0.649 Uzp=-1.124, -1.124
Add= 49 RD=0.351, 0.948 Uzp=-0.653, -0.653
Add= 50 RD=0.052, 0.649 Uzp=-1.124, -1.124
Add= 51 RD=0.351, 0.948 Uzp=-0.653, -0.653
Add= 52 RD=0.052, 0.649 Uzp=-1.124, -1.124
Add= 53 RD=0.351, 0.948 Uzp=-0.653, -0.653
Add= 54 RD=0.052, 0.649 Uzp=-1.124, -1.124
Add= 55 RD=0.351, 0.948 Uzp=-0.653, -0.653
Add= 56 RD=0.052, 0.649 Uzp=-1.124, -1.124
Add= 57 RD=0.351, 0.948 Uzp=-0.653, -0.653
Add= 58 RD=0.052, 0.649 Uzp=-1.124, -1.124
Add= 59 RD=0.351, 0.948 Uzp=-0.653, -0.653
Add= 60 RD=0.052, 0.649 Uzp=-1.124, -1.124
Add= 61 RD=0.351, 0.948 Uzp=-0.653, -0.653
Add= 62 RD=0.052, 0.649 Uzp=-1.124, -1.124
Add= 63 RD=0.351, 0.948 Uzp=-0.653, -0.653
Add= 64 RD=0.052, 0.649 Uzp=-1.124, -1.124
Add= 65 RD=0.351, 0.948 Uzp=-0.653, -0.653
Add= 66 RD=0.052, 0.649 Uzp=-1.124, -1.124
Add= 67 RD=0.351, 0.948 Uzp=-0.653, -0.653
Add= 68 RD=0.052, 0.649 Uzp=-1.124, -1.124
Add= 69 RD=0.351, 0.948 Uzp=-0.653, -0.653
Add= 70 RD=0.052, 0.649 Uzp=-1.124, -1.124

Add= 71 RD=0.351, 0.948 Uzp=-0.653, -0.653
Add= 72 RD=0.052, 0.649 Uzp=-1.124, -1.124
Add= 73 RD=0.351, 0.948 Uzp=-0.653, -0.653
Add= 74 RD=0.052, 0.649 Uzp=-1.124, -1.124
Add= 75 RD=0.351, 0.948 Uzp=-0.653, -0.653
Add= 76 RD=0.052, 0.649 Uzp=-1.124, -1.124
Add= 77 RD=0.351, 0.948 Uzp=-0.653, -0.653
Add= 78 RD=0.052, 0.649 Uzp=-1.124, -1.124
Add= 79 RD=0.351, 0.948 Uzp=-0.653, -0.653
Add= 80 RD=0.052, 0.649 Uzp=-1.124, -1.124
Add= 81 RD=0.351, 0.948 Uzp=-0.653, -0.653
Add= 82 RD=0.052, 0.649 Uzp=-1.124, -1.124
Add= 83 RD=0.351, 0.948 Uzp=-0.653, -0.653
Add= 84 RD=0.052, 0.649 Uzp=-1.124, -1.124

COMBO
Name=STEEL Type=ADD :
LOAD=STEEL sf=1.000

Name=CONC Type=ADD :
LOAD=CONC sf=1.000
LOAD=CR-HUNCH sf=1.000

OUTPUT
ELEM=JOINT TYPE=DISP,REAC LOAD=* COMB=*
ELEM=FRAME TYPE=FORCE LOAD=* COMB=*

2) 합성 후
< AFTER COMPOSITE SELF-WEIGHT LOAD >

```
SYSTEM
LENGTH=M                FORCE=KN

JOINT
1  X= 0.000    Y=0.000    Z=0.000
2  X= 4.450    Y=0.000    Z=0.000
3  X= 9.450    Y=0.000    Z=0.000
4  X= 14.450   Y=0.000    Z=0.000
5  X= 19.450   Y=0.000    Z=0.000
6  X= 24.450   Y=0.000    Z=0.000
7  X= 29.450   Y=0.000    Z=0.000
8  X= 34.450   Y=0.000    Z=0.000
9  X= 39.450   Y=0.000    Z=0.000
10  X= 44.450   Y=0.000    Z=0.000
11  X= 49.450   Y=0.000    Z=0.000
12  X= 54.450   Y=0.000    Z=0.000
13  X= 59.450   Y=0.000    Z=0.000
14  X= 64.450   Y=0.000    Z=0.000
15  X= 69.450   Y=0.000    Z=0.000
16  X= 74.450   Y=0.000    Z=0.000
17  X= 79.450   Y=0.000    Z=0.000
18  X= 84.450   Y=0.000    Z=0.000
19  X= 89.450   Y=0.000    Z=0.000
20  X= 94.450   Y=0.000    Z=0.000
21  X= 99.450   Y=0.000    Z=0.000
22  X= 104.030   Y=0.000    Z=0.000
23  X= 0.000    Y=-7.700    Z=-0.154
24  X= 4.450    Y=-7.700    Z=-0.154
25  X= 9.450    Y=-7.700    Z=-0.154
26  X= 14.450   Y=-7.700    Z=-0.154
27  X= 19.450   Y=-7.700    Z=-0.154
28  X= 24.450   Y=-7.700    Z=-0.154
29  X= 29.450   Y=-7.700    Z=-0.154
30  X= 34.450   Y=-7.700    Z=-0.154
31  X= 39.450   Y=-7.700    Z=-0.154
32  X= 44.450   Y=-7.700    Z=-0.154
33  X= 49.450   Y=-7.700    Z=-0.154
34  X= 54.450   Y=-7.700    Z=-0.154
35  X= 59.450   Y=-7.700    Z=-0.154
36  X= 64.450   Y=-7.700    Z=-0.154
37  X= 69.450   Y=-7.700    Z=-0.154
38  X= 74.450   Y=-7.700    Z=-0.154
39  X= 79.450   Y=-7.700    Z=-0.154
40  X= 84.450   Y=-7.700    Z=-0.154
41  X= 89.450   Y=-7.700    Z=-0.154
42  X= 94.450   Y=-7.700    Z=-0.154
43  X= 99.450   Y=-7.700    Z=-0.154
44  X= 104.030   Y=-7.700    Z=-0.154
45  X= 0.000    Y=-3.850    Z=-0.077
46  X= 4.450    Y=-3.850    Z=-0.077
47  X= 9.450    Y=-3.850    Z=-0.077
48  X= 14.450   Y=-3.850    Z=-0.077
49  X= 19.450   Y=-3.850    Z=-0.077
50  X= 24.450   Y=-3.850    Z=-0.077
51  X= 29.450   Y=-3.850    Z=-0.077
52  X= 34.450   Y=-3.850    Z=-0.077
53  X= 39.450   Y=-3.850    Z=-0.077
54  X= 44.450   Y=-3.850    Z=-0.077
55  X= 49.450   Y=-3.850    Z=-0.077
56  X= 54.450   Y=-3.850    Z=-0.077
57  X= 59.450   Y=-3.850    Z=-0.077
58  X= 64.450   Y=-3.850    Z=-0.077
59  X= 69.450   Y=-3.850    Z=-0.077
60  X= 74.450   Y=-3.850    Z=-0.077
61  X= 79.450   Y=-3.850    Z=-0.077
62  X= 84.450   Y=-3.850    Z=-0.077
63  X= 89.450   Y=-3.850    Z=-0.077
64  X= 94.450   Y=-3.850    Z=-0.077
65  X= 99.450   Y=-3.850    Z=-0.077
66  X= 104.030   Y=-3.850    Z=-0.077
```



```
67  X= 0.000    Y=0.000    Z=-1.150
68  X= 0.000    Y=1.050    Z=-1.150
69  X= 0.000    Y=-1.050    Z=-1.150
70  X= 54.450    Y=0.000    Z=-1.250
71  X= 54.450    Y=1.050    Z=-1.250
72  X= 54.450    Y=-1.050    Z=-1.250
73  X= 104.030    Y=0.000    Z=-1.150
74  X= 104.030    Y=1.050    Z=-1.150
75  X= 104.030    Y=-1.050    Z=-1.150
76  X= 0.000    Y=-7.700    Z=-1.304
77  X= 0.000    Y=-6.650    Z=-1.304
78  X= 0.000    Y=-8.750    Z=-1.304
79  X= 54.450    Y=-7.700    Z=-1.404
80  X= 54.450    Y=-6.650    Z=-1.404
81  X= 54.450    Y=-8.750    Z=-1.404
82  X= 104.030    Y=-7.700    Z=-1.304
83  X= 104.030    Y=-6.650    Z=-1.304
84  X= 104.030    Y=-8.750    Z=-1.304

LOCAL
ADD=  68  ANG=0.000
ADD=  69  ANG=0.000
ADD=  71  ANG=0.000
ADD=  72  ANG=0.000
ADD=  74  ANG=0.000
ADD=  75  ANG=0.000
ADD=  77  ANG=5.872
ADD=  78  ANG=8.049
ADD=  80  ANG=0.000
ADD=  81  ANG=0.000
ADD=  83  ANG=-6.444
ADD=  84  ANG=-8.828

RESTRAINT
ADD=  68  DOF=      U2, U3,
ADD=  69  DOF=      U2, U3,
ADD=  71  DOF= U1, U2, U3,
ADD=  72  DOF= U1, U2, U3,
ADD=  74  DOF=      U2, U3,
ADD=  75  DOF=      U2, U3,
ADD=  77  DOF=          U3,
ADD=  78  DOF=          U3,
ADD=  80  DOF= U1,      U3,
ADD=  81  DOF= U1,      U3,
ADD=  83  DOF=          U3,
ADD=  84  DOF=          U3,

MATERIAL
Name=1
E=2.05e+008
Name=2
E=2.05e+008
Name=3
E=2.05e+008
Name=4
E=2.05e+008
Name=5
E=2.05e+008
Name=6
E=2.05e+008
Name=7
E=2.05e+008
Name=8
E=2.05e+008
Name=9
E=2.05e+008
Name=10
E=2.05e+008
Name=11
E=2.05e+008
Name=12
E=2.05e+008
Name=13
```



```
E=2.05e+008
Name=14
E=2.05e+008
Name=15
E=2.05e+008
Name=16
E=2.05e+008
Name=17
E=2.05e+008
Name=18
E=2.05e+008
Name=19
E=2.05e+008
Name=20
E=2.05e+008
Name=21
E=2.05e+008

FRAME SECTION
Name=   1  Mat=   1  A=0.31086  I=0.23700884, 0.81280104  J=0.19666515    ; GIRDER
Name=   2  Mat=   2  A=0.31486  I=0.28250528, 0.82062503  J=0.22101250    ; GIRDER
Name=   3  Mat=   3  A=0.32662  I=0.33306917, 0.83043848  J=0.24351348    ; GIRDER
Name=   4  Mat=   4  A=0.36190  I=0.40869340, 0.85935523  J=0.26781294    ; GIRDER
Name=   5  Mat=   5  A=0.37282  I=0.44508691, 0.86633164  J=0.26781294    ; GIRDER
Name=   6  Mat=   6  A=0.34706  I=0.39688457, 0.84641193  J=0.25410445    ; GIRDER
Name=   7  Mat=   7  A=0.45526  I=0.58100343, 0.95508413  J=0.38096295    ; GIRDER
Name=   8  Mat=   8  A=0.35014  I=0.38385500, 0.85582068  J=0.26087422    ; GIRDER
Name=   9  Mat=   9  A=0.33838  I=0.38030356, 0.84015859  J=0.25819292    ; GIRDER
Name=   10  Mat=   10  A=0.30466  I=0.23540042, 0.75928243  J=0.19666515    ; GIRDER
Name=   11  Mat=   11  A=0.30866  I=0.28057184, 0.76728296  J=0.22101250    ; GIRDER
Name=   12  Mat=   12  A=0.32042  I=0.33057213, 0.77758860  J=0.24351348    ; GIRDER
Name=   13  Mat=   13  A=0.35570  I=0.40556776, 0.80777754  J=0.26781294    ; GIRDER
Name=   14  Mat=   14  A=0.36662  I=0.44146450, 0.81509583  J=0.26781294    ; GIRDER
Name=   15  Mat=   15  A=0.34086  I=0.39364487, 0.79433278  J=0.25410445    ; GIRDER
Name=   16  Mat=   16  A=0.44906  I=0.57632641, 0.90587243  J=0.38096295    ; GIRDER
Name=   17  Mat=   17  A=0.34394  I=0.38093229, 0.80384935  J=0.26087422    ; GIRDER
Name=   18  Mat=   18  A=0.33218  I=0.37721604, 0.78776432  J=0.25819292    ; GIRDER
Name=   19  Mat=   19  A=0.02880  I=0.01174211, 0.00005426  J=0.00000138    ; CROSSBEAM
Name=   20  Mat=   20  A=0.01680  I=0.00169991, 0.00005412  J=0.00000081    ; STRINGER
Name=   21  Mat=   21  A=10.00000  I=10.00000000, 10.00000000  J=10.00000000    ; SHOE
Name=   22  Type=Nonpr  Sec=    1,    2  Elvar=2,1
Name=   23  Type=Nonpr  Sec=    2,    1
Name=   24  Type=Nonpr  Sec=    2,    3
Name=   25  Type=Nonpr  Sec=    3,    4
Name=   26  Type=Nonpr  Sec=    4,    5
Name=   27  Type=Nonpr  Sec=    5,    6
Name=   28  Type=Nonpr  Sec=    6,    7
Name=   29  Type=Nonpr  Sec=    6,    8
Name=   30  Type=Nonpr  Sec=    7,    6
Name=   31  Type=Nonpr  Sec=    8,    9
Name=   32  Type=Nonpr  Sec=    9,    2
Name=   33  Type=Nonpr  Sec=   10,   11
Name=   34  Type=Nonpr  Sec=   11,   10
Name=   35  Type=Nonpr  Sec=   11,   12
Name=   36  Type=Nonpr  Sec=   12,   13
Name=   37  Type=Nonpr  Sec=   13,   14
Name=   38  Type=Nonpr  Sec=   14,   15
Name=   39  Type=Nonpr  Sec=   15,   16
Name=   40  Type=Nonpr  Sec=   15,   17
Name=   41  Type=Nonpr  Sec=   16,   15
Name=   42  Type=Nonpr  Sec=   17,   18
Name=   43  Type=Nonpr  Sec=   18,   11

FRAME
1  J=  1,   2  Sec=22  Local=12  Pldir=+Z,+X  NSEG=4
2  J=  2,   3  Sec=24
3  J=  3,   4  Sec=25
4  J=  4,   5  Sec= 4
5  J=  5,   6  Sec= 4
6  J=  6,   7  Sec= 4
7  J=  7,   8  Sec= 4
8  J=  8,   9  Sec=26
9  J=  9,  10  Sec=27
```



```
10  J=  10,  11  Sec=28
11  J=  11,  12  Sec= 7
12  J=  12,  13  Sec= 7
13  J=  13,  14  Sec=30
14  J=  14,  15  Sec=29
15  J=  15,  16  Sec= 8
16  J=  16,  17  Sec= 8
17  J=  17,  18  Sec= 8
18  J=  18,  19  Sec= 8
19  J=  19,  20  Sec=31
20  J=  20,  21  Sec=32
21  J=  21,  22  Sec=23
22  J=  23,  24  Sec=33
23  J=  24,  25  Sec=35
24  J=  25,  26  Sec=36
25  J=  26,  27  Sec=13
26  J=  27,  28  Sec=13
27  J=  28,  29  Sec=13
28  J=  29,  30  Sec=13
29  J=  30,  31  Sec=37
30  J=  31,  32  Sec=38
31  J=  32,  33  Sec=39
32  J=  33,  34  Sec=16
33  J=  34,  35  Sec=16
34  J=  35,  36  Sec=41
35  J=  36,  37  Sec=40
36  J=  37,  38  Sec=17
37  J=  38,  39  Sec=17
38  J=  39,  40  Sec=17
39  J=  40,  41  Sec=17
40  J=  41,  42  Sec=42
41  J=  42,  43  Sec=43
42  J=  43,  44  Sec=34
43  J=  1,  45  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
44  J=  45,  23  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
45  J=  2,  46  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
46  J=  46,  24  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
47  J=  3,  47  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
48  J=  47,  25  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
49  J=  4,  48  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
50  J=  48,  26  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
51  J=  5,  49  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
52  J=  49,  27  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
53  J=  6,  50  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
54  J=  50,  28  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
55  J=  7,  51  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
56  J=  51,  29  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
57  J=  8,  52  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
58  J=  52,  30  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
59  J=  9,  53  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
60  J=  53,  31  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
61  J=  10,  54  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
62  J=  54,  32  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
63  J=  11,  55  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
64  J=  55,  33  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
65  J=  12,  56  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
66  J=  56,  34  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
67  J=  13,  57  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
68  J=  57,  35  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
69  J=  14,  58  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
70  J=  58,  36  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
71  J=  15,  59  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
72  J=  59,  37  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
73  J=  16,  60  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
74  J=  60,  38  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
75  J=  17,  61  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
76  J=  61,  39  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
77  J=  18,  62  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
78  J=  62,  40  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
79  J=  19,  63  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
80  J=  63,  41  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
81  J=  20,  64  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
82  J=  64,  42  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
```

```
83  J= 21,  65  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
84  J= 65,  43  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
85  J= 22,  66  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
86  J= 66,  44  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
87  J= 45,  46  Sec=20
88  J= 46,  47  Sec=20
89  J= 47,  48  Sec=20
90  J= 48,  49  Sec=20
91  J= 49,  50  Sec=20
92  J= 50,  51  Sec=20
93  J= 51,  52  Sec=20
94  J= 52,  53  Sec=20
95  J= 53,  54  Sec=20
96  J= 54,  55  Sec=20
97  J= 55,  56  Sec=20
98  J= 56,  57  Sec=20
99  J= 57,  58  Sec=20
100 J= 58,  59  Sec=20
101 J= 59,  60  Sec=20
102 J= 60,  61  Sec=20
103 J= 61,  62  Sec=20
104 J= 62,  63  Sec=20
105 J= 63,  64  Sec=20
106 J= 64,  65  Sec=20
107 J= 65,  66  Sec=20
108 J=  1,  67  Sec=21
109 J= 68,  67  Sec=21
110 J= 69,  67  Sec=21
111 J= 12,  70  Sec=21
112 J= 71,  70  Sec=21
113 J= 72,  70  Sec=21
114 J= 22,  73  Sec=21
115 J= 74,  73  Sec=21
116 J= 75,  73  Sec=21
117 J= 23,  76  Sec=21
118 J= 77,  76  Sec=21
119 J= 78,  76  Sec=21
120 J= 34,  79  Sec=21
121 J= 80,  79  Sec=21
122 J= 81,  79  Sec=21
123 J= 44,  82  Sec=21
124 J= 83,  82  Sec=21
125 J= 84,  82  Sec=21

LOAD
Name=AFTER  ;  AFTER SELF-WEIGHT LOAD (부속시설하중 포함)
Type=Distributed Span
Add=  1  RD=0.000, 1.000  Uzp=-19.076, -19.076  R1=-23.820, -23.820
Add=  2  RD=0.000, 1.000  Uzp=-19.076, -19.076  R1=-23.820, -23.820
Add=  3  RD=0.000, 1.000  Uzp=-19.076, -19.076  R1=-23.820, -23.820
Add=  4  RD=0.000, 1.000  Uzp=-19.076, -19.076  R1=-23.820, -23.820
Add=  5  RD=0.000, 1.000  Uzp=-19.076, -19.076  R1=-23.820, -23.820
Add=  6  RD=0.000, 1.000  Uzp=-19.076, -19.076  R1=-23.820, -23.820
Add=  7  RD=0.000, 1.000  Uzp=-19.076, -19.076  R1=-23.820, -23.820
Add=  8  RD=0.000, 1.000  Uzp=-19.076, -19.076  R1=-23.820, -23.820
Add=  9  RD=0.000, 1.000  Uzp=-19.076, -19.076  R1=-23.820, -23.820
Add= 10  RD=0.000, 1.000  Uzp=-19.076, -19.076  R1=-23.820, -23.820
Add= 11  RD=0.000, 1.000  Uzp=-19.076, -19.076  R1=-23.820, -23.820
Add= 12  RD=0.000, 1.000  Uzp=-19.076, -19.076  R1=-23.820, -23.820
Add= 13  RD=0.000, 1.000  Uzp=-19.076, -19.076  R1=-23.820, -23.820
Add= 14  RD=0.000, 1.000  Uzp=-19.076, -19.076  R1=-23.820, -23.820
Add= 15  RD=0.000, 1.000  Uzp=-19.076, -19.076  R1=-23.820, -23.820
Add= 16  RD=0.000, 1.000  Uzp=-19.076, -19.076  R1=-23.820, -23.820
Add= 17  RD=0.000, 1.000  Uzp=-19.076, -19.076  R1=-23.820, -23.820
Add= 18  RD=0.000, 1.000  Uzp=-19.076, -19.076  R1=-23.820, -23.820
Add= 19  RD=0.000, 1.000  Uzp=-19.076, -19.076  R1=-23.820, -23.820
Add= 20  RD=0.000, 1.000  Uzp=-19.076, -19.076  R1=-23.820, -23.820
Add= 21  RD=0.000, 1.000  Uzp=-19.076, -19.076  R1=-23.820, -23.820
Add= 22  RD=0.000, 1.000  Uzp=-18.699, -18.699  R1=16.856, 16.856
Add= 23  RD=0.000, 1.000  Uzp=-18.699, -18.699  R1=16.856, 16.856
Add= 24  RD=0.000, 1.000  Uzp=-18.699, -18.699  R1=16.856, 16.856
Add= 25  RD=0.000, 1.000  Uzp=-18.699, -18.699  R1=16.856, 16.856
Add= 26  RD=0.000, 1.000  Uzp=-18.699, -18.699  R1=16.856, 16.856
Add= 27  RD=0.000, 1.000  Uzp=-18.699, -18.699  R1=16.856, 16.856
Add= 28  RD=0.000, 1.000  Uzp=-18.699, -18.699  R1=16.856, 16.856
```



```
Add= 29  RD=0.000, 1.000  Uzp=-18.699, -18.699  R1=16.856, 16.856
Add= 30  RD=0.000, 1.000  Uzp=-18.699, -18.699  R1=16.856, 16.856
Add= 31  RD=0.000, 1.000  Uzp=-18.699, -18.699  R1=16.856, 16.856
Add= 32  RD=0.000, 1.000  Uzp=-18.699, -18.699  R1=16.856, 16.856
Add= 33  RD=0.000, 1.000  Uzp=-18.699, -18.699  R1=16.856, 16.856
Add= 34  RD=0.000, 1.000  Uzp=-18.699, -18.699  R1=16.856, 16.856
Add= 35  RD=0.000, 1.000  Uzp=-18.699, -18.699  R1=16.856, 16.856
Add= 36  RD=0.000, 1.000  Uzp=-18.699, -18.699  R1=16.856, 16.856
Add= 37  RD=0.000, 1.000  Uzp=-18.699, -18.699  R1=16.856, 16.856
Add= 38  RD=0.000, 1.000  Uzp=-18.699, -18.699  R1=16.856, 16.856
Add= 39  RD=0.000, 1.000  Uzp=-18.699, -18.699  R1=16.856, 16.856
Add= 40  RD=0.000, 1.000  Uzp=-18.699, -18.699  R1=16.856, 16.856
Add= 41  RD=0.000, 1.000  Uzp=-18.699, -18.699  R1=16.856, 16.856
Add= 42  RD=0.000, 1.000  Uzp=-18.699, -18.699  R1=16.856, 16.856
Add= 87  RD=0.000, 1.000  Uzp=-6.893, -6.893
Add= 88  RD=0.000, 1.000  Uzp=-6.893, -6.893
Add= 89  RD=0.000, 1.000  Uzp=-6.893, -6.893
Add= 90  RD=0.000, 1.000  Uzp=-6.893, -6.893
Add= 91  RD=0.000, 1.000  Uzp=-6.893, -6.893
Add= 92  RD=0.000, 1.000  Uzp=-6.893, -6.893
Add= 93  RD=0.000, 1.000  Uzp=-6.893, -6.893
Add= 94  RD=0.000, 1.000  Uzp=-6.893, -6.893
Add= 95  RD=0.000, 1.000  Uzp=-6.893, -6.893
Add= 96  RD=0.000, 1.000  Uzp=-6.893, -6.893
Add= 97  RD=0.000, 1.000  Uzp=-6.893, -6.893
Add= 98  RD=0.000, 1.000  Uzp=-6.893, -6.893
Add= 99  RD=0.000, 1.000  Uzp=-6.893, -6.893
Add=100  RD=0.000, 1.000  Uzp=-6.893, -6.893
Add=101  RD=0.000, 1.000  Uzp=-6.893, -6.893
Add=102  RD=0.000, 1.000  Uzp=-6.893, -6.893
Add=103  RD=0.000, 1.000  Uzp=-6.893, -6.893
Add=104  RD=0.000, 1.000  Uzp=-6.893, -6.893
Add=105  RD=0.000, 1.000  Uzp=-6.893, -6.893
Add=106  RD=0.000, 1.000  Uzp=-6.893, -6.893
Add=107  RD=0.000, 1.000  Uzp=-6.893, -6.893

COMBO
Name=AFTER  Type=ADD  ;
LOAD=AFTER  sf=1.000

OUTPUT
ELEM=JOINT   TYPE=DISP,REAC      LOAD=*   COMB=*
ELEM=FRAME   TYPE=FORCE          LOAD=*   COMB=*
```


3) 탈하중 재하시
< MOVING LOAD >

```
SYSTEM
LENGTH=M                FORCE=KN

JOINT
1   X= 0.000    Y=0.000    Z=0.000
2   X= 4.450    Y=0.000    Z=0.000
3   X= 9.450    Y=0.000    Z=0.000
4   X= 14.450   Y=0.000    Z=0.000
5   X= 19.450   Y=0.000    Z=0.000
6   X= 24.450   Y=0.000    Z=0.000
7   X= 29.450   Y=0.000    Z=0.000
8   X= 34.450   Y=0.000    Z=0.000
9   X= 39.450   Y=0.000    Z=0.000
10  X= 44.450   Y=0.000    Z=0.000
11  X= 49.450   Y=0.000    Z=0.000
12  X= 54.450   Y=0.000    Z=0.000
13  X= 59.450   Y=0.000    Z=0.000
14  X= 64.450   Y=0.000    Z=0.000
15  X= 69.450   Y=0.000    Z=0.000
16  X= 74.450   Y=0.000    Z=0.000
17  X= 79.450   Y=0.000    Z=0.000
18  X= 84.450   Y=0.000    Z=0.000
19  X= 89.450   Y=0.000    Z=0.000
20  X= 94.450   Y=0.000    Z=0.000
21  X= 99.450   Y=0.000    Z=0.000
22  X= 104.030  Y=0.000    Z=0.000
23  X= 0.000    Y=-7.700   Z=-0.154
24  X= 4.450    Y=-7.700   Z=-0.154
25  X= 9.450    Y=-7.700   Z=-0.154
26  X= 14.450   Y=-7.700   Z=-0.154
27  X= 19.450   Y=-7.700   Z=-0.154
28  X= 24.450   Y=-7.700   Z=-0.154
29  X= 29.450   Y=-7.700   Z=-0.154
30  X= 34.450   Y=-7.700   Z=-0.154
31  X= 39.450   Y=-7.700   Z=-0.154
32  X= 44.450   Y=-7.700   Z=-0.154
33  X= 49.450   Y=-7.700   Z=-0.154
34  X= 54.450   Y=-7.700   Z=-0.154
35  X= 59.450   Y=-7.700   Z=-0.154
36  X= 64.450   Y=-7.700   Z=-0.154
37  X= 69.450   Y=-7.700   Z=-0.154
38  X= 74.450   Y=-7.700   Z=-0.154
39  X= 79.450   Y=-7.700   Z=-0.154
40  X= 84.450   Y=-7.700   Z=-0.154
41  X= 89.450   Y=-7.700   Z=-0.154
42  X= 94.450   Y=-7.700   Z=-0.154
43  X= 99.450   Y=-7.700   Z=-0.154
44  X= 104.030  Y=-7.700   Z=-0.154
45  X= 0.000    Y=-3.850   Z=-0.077
46  X= 4.450    Y=-3.850   Z=-0.077
47  X= 9.450    Y=-3.850   Z=-0.077
48  X= 14.450   Y=-3.850   Z=-0.077
49  X= 19.450   Y=-3.850   Z=-0.077
50  X= 24.450   Y=-3.850   Z=-0.077
51  X= 29.450   Y=-3.850   Z=-0.077
52  X= 34.450   Y=-3.850   Z=-0.077
53  X= 39.450   Y=-3.850   Z=-0.077
54  X= 44.450   Y=-3.850   Z=-0.077
55  X= 49.450   Y=-3.850   Z=-0.077
56  X= 54.450   Y=-3.850   Z=-0.077
57  X= 59.450   Y=-3.850   Z=-0.077
58  X= 64.450   Y=-3.850   Z=-0.077
59  X= 69.450   Y=-3.850   Z=-0.077
60  X= 74.450   Y=-3.850   Z=-0.077
61  X= 79.450   Y=-3.850   Z=-0.077
62  X= 84.450   Y=-3.850   Z=-0.077
63  X= 89.450   Y=-3.850   Z=-0.077
64  X= 94.450   Y=-3.850   Z=-0.077
65  X= 99.450   Y=-3.850   Z=-0.077
66  X= 104.030  Y=-3.850   Z=-0.077
```



```
67  X= 0.000    Y=0.000    Z=-1.150
68  X= 0.000    Y=1.050    Z=-1.150
69  X= 0.000    Y=-1.050   Z=-1.150
70  X= 54.450   Y=0.000    Z=-1.250
71  X= 54.450   Y=1.050    Z=-1.250
72  X= 54.450   Y=-1.050   Z=-1.250
73  X= 104.030  Y=0.000    Z=-1.150
74  X= 104.030  Y=1.050    Z=-1.150
75  X= 104.030  Y=-1.050   Z=-1.150
76  X= 0.000    Y=-7.700   Z=-1.304
77  X= 0.000    Y=-6.650   Z=-1.304
78  X= 0.000    Y=-8.750   Z=-1.304
79  X= 54.450   Y=-7.700   Z=-1.404
80  X= 54.450   Y=-6.650   Z=-1.404
81  X= 54.450   Y=-8.750   Z=-1.404
82  X= 104.030  Y=-7.700   Z=-1.304
83  X= 104.030  Y=-6.650   Z=-1.304
84  X= 104.030  Y=-8.750   Z=-1.304

LOCAL
ADD=  68  ANG=0.000
ADD=  69  ANG=0.000
ADD=  71  ANG=0.000
ADD=  72  ANG=0.000
ADD=  74  ANG=0.000
ADD=  75  ANG=0.000
ADD=  77  ANG=5.872
ADD=  78  ANG=8.049
ADD=  80  ANG=0.000
ADD=  81  ANG=0.000
ADD=  83  ANG=-6.444
ADD=  84  ANG=-8.828

RESTRAINT
ADD=  68  DOF=      U2, U3,
ADD=  69  DOF=      U2, U3,
ADD=  71  DOF= U1, U2, U3,
ADD=  72  DOF= U1, U2, U3,
ADD=  74  DOF=      U2, U3,
ADD=  75  DOF=      U2, U3,
ADD=  77  DOF=          U3,
ADD=  78  DOF=          U3,
ADD=  80  DOF= U1,      U3,
ADD=  81  DOF= U1,      U3,
ADD=  83  DOF=          U3,
ADD=  84  DOF=          U3,

MATERIAL
Name=1
E=2.05e+008
Name=2
E=2.05e+008
Name=3
E=2.05e+008
Name=4
E=2.05e+008
Name=5
E=2.05e+008
Name=6
E=2.05e+008
Name=7
E=2.05e+008
Name=8
E=2.05e+008
Name=9
E=2.05e+008
Name=10
E=2.05e+008
Name=11
E=2.05e+008
Name=12
E=2.05e+008
Name=13
```

```
E=2.05e+008
Name=14
E=2.05e+008
Name=15
E=2.05e+008
Name=16
E=2.05e+008
Name=17
E=2.05e+008
Name=18
E=2.05e+008
Name=19
E=2.05e+008
Name=20
E=2.05e+008
Name=21
E=2.05e+008

FRAME SECTION
Name=   1  Mat=   1  A=0.31086  I=0.23700884, 0.81280104  J=0.19666515    : GIRDER
Name=   2  Mat=   2  A=0.31486  I=0.28250528, 0.82062503  J=0.22101250    : GIRDER
Name=   3  Mat=   3  A=0.32662  I=0.33306917, 0.83043848  J=0.24351348    : GIRDER
Name=   4  Mat=   4  A=0.36190  I=0.40869340, 0.85935523  J=0.26781294    : GIRDER
Name=   5  Mat=   5  A=0.37282  I=0.44508691, 0.86633164  J=0.26781294    : GIRDER
Name=   6  Mat=   6  A=0.34706  I=0.39688457, 0.84641193  J=0.25410445    : GIRDER
Name=   7  Mat=   7  A=0.45526  I=0.58100343, 0.95508413  J=0.38096295    : GIRDER
Name=   8  Mat=   8  A=0.35014  I=0.38385500, 0.85582068  J=0.26087422    : GIRDER
Name=   9  Mat=   9  A=0.33838  I=0.38030356, 0.84018859  J=0.25819292    : GIRDER
Name=  10  Mat=  10  A=0.30466  I=0.23540042, 0.75928243  J=0.19666515    : GIRDER
Name=  11  Mat=  11  A=0.30866  I=0.28057184, 0.76728296  J=0.22101250    : GIRDER
Name=  12  Mat=  12  A=0.32042  I=0.33057213, 0.77758860  J=0.24351348    : GIRDER
Name=  13  Mat=  13  A=0.35570  I=0.40556776, 0.80777754  J=0.26781294    : GIRDER
Name=  14  Mat=  14  A=0.36662  I=0.44146450, 0.81509583  J=0.26781294    : GIRDER
Name=  15  Mat=  15  A=0.34086  I=0.39364487, 0.79433278  J=0.25410445    : GIRDER
Name=  16  Mat=  16  A=0.44906  I=0.57632641, 0.90587243  J=0.38096295    : GIRDER
Name=  17  Mat=  17  A=0.34394  I=0.38093229, 0.80384935  J=0.26087422    : GIRDER
Name=  18  Mat=  18  A=0.33218  I=0.37721604, 0.78776432  J=0.25819292    : GIRDER
Name=  19  Mat=  19  A=0.02880  I=0.01174211, 0.00005426  J=0.00000138    : CROSSBEAM
Name=  20  Mat=  20  A=0.01680  I=0.00169891, 0.00005412  J=0.00000081    : STRINGER
Name=  21  Mat=  21  A=10.00000  I=10.00000000, 10.00000000  J=10.00000000    : SHOE
Name=  22  Type=Nonpr  Sec=    1,    2  Elvar=2.1
Name=  23  Type=Nonpr  Sec=    2,    1
Name=  24  Type=Nonpr  Sec=    2,    3
Name=  25  Type=Nonpr  Sec=    3,    4
Name=  26  Type=Nonpr  Sec=    4,    5
Name=  27  Type=Nonpr  Sec=    5,    6
Name=  28  Type=Nonpr  Sec=    6,    7
Name=  29  Type=Nonpr  Sec=    6,    8
Name=  30  Type=Nonpr  Sec=    7,    6
Name=  31  Type=Nonpr  Sec=    8,    9
Name=  32  Type=Nonpr  Sec=    9,    2
Name=  33  Type=Nonpr  Sec=   10,   11
Name=  34  Type=Nonpr  Sec=   11,   10
Name=  35  Type=Nonpr  Sec=   11,   12
Name=  36  Type=Nonpr  Sec=   12,   13
Name=  37  Type=Nonpr  Sec=   13,   14
Name=  38  Type=Nonpr  Sec=   14,   15
Name=  39  Type=Nonpr  Sec=   15,   16
Name=  40  Type=Nonpr  Sec=   15,   17
Name=  41  Type=Nonpr  Sec=   16,   15
Name=  42  Type=Nonpr  Sec=   17,   18
Name=  43  Type=Nonpr  Sec=   18,   11

FRAME
1  J=  1,   2  Sec=22  Local=12  Pldir=+Z,+X  NSEG=4
2  J=  2,   3  Sec=24
3  J=  3,   4  Sec=25
4  J=  4,   5  Sec= 4
5  J=  5,   6  Sec= 4
6  J=  6,   7  Sec= 4
7  J=  7,   8  Sec= 4
8  J=  8,   9  Sec=26
9  J=  9,  10  Sec=27
```



```
10  J= 10,  11  Sec=28
11  J= 11,  12  Sec= 7
12  J= 12,  13  Sec= 7
13  J= 13,  14  Sec=30
14  J= 14,  15  Sec=29
15  J= 15,  16  Sec= 8
16  J= 16,  17  Sec= 8
17  J= 17,  18  Sec= 8
18  J= 18,  19  Sec= 8
19  J= 19,  20  Sec=31
20  J= 20,  21  Sec=32
21  J= 21,  22  Sec=23
22  J= 23,  24  Sec=33
23  J= 24,  25  Sec=35
24  J= 25,  26  Sec=36
25  J= 26,  27  Sec=13
26  J= 27,  28  Sec=13
27  J= 28,  29  Sec=13
28  J= 29,  30  Sec=13
29  J= 30,  31  Sec=37
30  J= 31,  32  Sec=38
31  J= 32,  33  Sec=39
32  J= 33,  34  Sec=16
33  J= 34,  35  Sec=16
34  J= 35,  36  Sec=41
35  J= 36,  37  Sec=40
36  J= 37,  38  Sec=17
37  J= 38,  39  Sec=17
38  J= 39,  40  Sec=17
39  J= 40,  41  Sec=17
40  J= 41,  42  Sec=42
41  J= 42,  43  Sec=43
42  J= 43,  44  Sec=34
43  J=  1,  45  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
44  J= 45,  23  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
45  J=  2,  46  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
46  J= 46,  24  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
47  J=  3,  47  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
48  J= 47,  25  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
49  J=  4,  48  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
50  J= 48,  26  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
51  J=  5,  49  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
52  J= 49,  27  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
53  J=  6,  50  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
54  J= 50,  28  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
55  J=  7,  51  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
56  J= 51,  29  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
57  J=  8,  52  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
58  J= 52,  30  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
59  J=  9,  53  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
60  J= 53,  31  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
61  J= 10,  54  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
62  J= 54,  32  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
63  J= 11,  55  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
64  J= 55,  33  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
65  J= 12,  56  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
66  J= 56,  34  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
67  J= 13,  57  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
68  J= 57,  35  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
69  J= 14,  58  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
70  J= 58,  36  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
71  J= 15,  59  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
72  J= 59,  37  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
73  J= 16,  60  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
74  J= 60,  38  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
75  J= 17,  61  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
76  J= 61,  39  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
77  J= 18,  62  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
78  J= 62,  40  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
79  J= 19,  63  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
80  J= 63,  41  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
81  J= 20,  64  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
82  J= 64,  42  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
```



```
83  J= 21,  65  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
84  J= 65,  43  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
85  J= 22,  66  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
86  J= 66,  44  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
87  J= 45,  46  Sec=20
88  J= 46,  47  Sec=20
89  J= 47,  48  Sec=20
90  J= 48,  49  Sec=20
91  J= 49,  50  Sec=20
92  J= 50,  51  Sec=20
93  J= 51,  52  Sec=20
94  J= 52,  53  Sec=20
95  J= 53,  54  Sec=20
96  J= 54,  55  Sec=20
97  J= 55,  56  Sec=20
98  J= 56,  57  Sec=20
99  J= 57,  58  Sec=20
100  J= 58,  59  Sec=20
101  J= 59,  60  Sec=20
102  J= 60,  61  Sec=20
103  J= 61,  62  Sec=20
104  J= 62,  63  Sec=20
105  J= 63,  64  Sec=20
106  J= 64,  65  Sec=20
107  J= 65,  66  Sec=20
108  J=  1,  67  Sec=21
109  J= 68,  67  Sec=21
110  J= 69,  67  Sec=21
111  J= 12,  70  Sec=21
112  J= 71,  70  Sec=21
113  J= 72,  70  Sec=21
114  J= 22,  73  Sec=21
115  J= 74,  73  Sec=21
116  J= 75,  73  Sec=21
117  J= 23,  76  Sec=21
118  J= 77,  76  Sec=21
119  J= 78,  76  Sec=21
120  J= 34,  79  Sec=21
121  J= 80,  79  Sec=21
122  J= 81,  79  Sec=21
123  J= 44,  82  Sec=21
124  J= 83,  82  Sec=21
125  J= 84,  82  Sec=21

LANE
; Case = 1 ------------- G1 Max DB 1선
Name=L1G1
Path=    1,    11,    1,  Ecc=0.514
Path=   12,    21,    1,  Ecc=0.514
Name=L1G1S1
Path=   87,    97,    1,  Ecc=0.000
Path=   98,   107,    1,  Ecc=0.000
Name=L1G2
Path=   22,    32,    1,  Ecc=1.830
Path=   33,    42,    1,  Ecc=1.830

; Case = 2 ------------- G1 Max DB 2선
Name=L2G1
Path=    1,    11,    1,  Ecc=-0.057
Path=   12,    21,    1,  Ecc=-0.057
Name=L2G1S1
Path=   87,    97,    1,  Ecc=0.000
Path=   98,   107,    1,  Ecc=0.000
Name=L2G2
Path=   22,    32,    1,  Ecc=1.830
Path=   33,    42,    1,  Ecc=1.830

; Case = 3 ------------- G1 Max DB 3선
Name=L3G1
Path=    1,    11,    1,  Ecc=-0.038
Path=   12,    21,    1,  Ecc=-0.038
Name=L3G1S1
Path=   87,    97,    1,  Ecc=0.000
```



```
Path=   98,   107,    1,  Ecc=0.000
Name=L3G2
Path=   22,    32,    1,  Ecc=1.028
Path=   33,    42,    1,  Ecc=1.028

; Case = 4 ------------- G2 Max DB 1선
Name=L4G1
Path=    1,    11,    1,  Ecc=-1.830
Path=   12,    21,    1,  Ecc=-1.830
Name=L4G1S1
Path=   87,    97,    1,  Ecc=0.000
Path=   98,   107,    1,  Ecc=0.000
Name=L4G2
Path=   22,    32,    1,  Ecc=-0.025
Path=   33,    42,    1,  Ecc=-0.025

; Case = 5 ------------- G2 Max DB 2선
Name=L5G1
Path=    1,    11,    1,  Ecc=-1.814
Path=   12,    21,    1,  Ecc=-1.814
Name=L5G1S1
Path=   87,    97,    1,  Ecc=0.000
Path=   98,   107,    1,  Ecc=0.000
Name=L5G2
Path=   22,    32,    1,  Ecc=0.294
Path=   33,    42,    1,  Ecc=0.294

; Case = 6 ------------- G2 Max DB 3선
Name=L6G1
Path=    1,    11,    1,  Ecc=-0.844
Path=   12,    21,    1,  Ecc=-0.844
Name=L6G1S1
Path=   87,    97,    1,  Ecc=0.000
Path=   98,   107,    1,  Ecc=0.000
Name=L6G2
Path=   22,    32,    1,  Ecc=0.298
Path=   33,    42,    1,  Ecc=0.298

; Case = 7 ------------- G1 Max DL 1선
Name=L7G1
Path=    1,    11,    1,  Ecc=0.508
Path=   12,    21,    1,  Ecc=0.508
Name=L7G1S1
Path=   87,    97,    1,  Ecc=0.000
Path=   98,   107,    1,  Ecc=0.000
Name=L7G2
Path=   22,    32,    1,  Ecc=1.830
Path=   33,    42,    1,  Ecc=1.830

; Case = 8 ------------- G1 Max DL 2선
Name=L8G1
Path=    1,    11,    1,  Ecc=-0.060
Path=   12,    21,    1,  Ecc=-0.060
Name=L8G1S1
Path=   87,    97,    1,  Ecc=0.000
Path=   98,   107,    1,  Ecc=0.000
Name=L8G2
Path=   22,    32,    1,  Ecc=1.835
Path=   33,    42,    1,  Ecc=1.835

; Case = 9 ------------- G1 Max DL 3선
Name=L9G1
Path=    1,    11,    1,  Ecc=-0.047
Path=   12,    21,    1,  Ecc=-0.047
Name=L9G1S1
Path=   87,    97,    1,  Ecc=0.000
Path=   98,   107,    1,  Ecc=0.000
Name=L9G2
Path=   22,    32,    1,  Ecc=1.054
Path=   33,    42,    1,  Ecc=1.054

; Case = 10 ------------- G2 Max DL 1선
Name=L10G1
```

```
Path=    1,    11,    1,  Ecc=-1.830
Path=   12,    21,    1,  Ecc=-1.830
Name=L10G1S1
Path=   87,    97,    1,  Ecc=0.000
Path=   98,   107,    1,  Ecc=0.000
Name=L10G2
Path=   22,    32,    1,  Ecc=-0.014
Path=   33,    42,    1,  Ecc=-0.014

; Case = 11 ---------- G2 Max DL 2선
Name=L11G1
Path=    1,    11,    1,  Ecc=-1.733
Path=   12,    21,    1,  Ecc=-1.733
Name=L11G1S1
Path=   87,    97,    1,  Ecc=0.000
Path=   98,   107,    1,  Ecc=0.000
Name=L11G2
Path=   22,    32,    1,  Ecc=0.292
Path=   33,    42,    1,  Ecc=0.292

; Case = 12 ---------- G2 Max DL 3선
Name=L12G1
Path=    1,    11,    1,  Ecc=-0.856
Path=   12,    21,    1,  Ecc=-0.856
Name=L12G1S1
Path=   87,    97,    1,  Ecc=0.000
Path=   98,   107,    1,  Ecc=0.000
Name=L12G2
Path=   22,    32,    1,  Ecc=0.301
Path=   33,    42,    1,  Ecc=0.301

VEHICLES
Name=1     TYPE=Gen  ; DB-24
P=24.000
D=4.200  P=96.000
D=4.200  9.000  P=96.000

Name=2     TYPE=Gen  ; DL-24
W=4.233      PM=36.000      PXM=52.000


Vehicle Class
Name=1
Vehi=1
Name=2
Vehi=2

Bridge Response
Elem=Frame
Add=*
Elem=Joint Type=DISP
Add=*
Elem=Joint Type=REAC
Add=*

MOVING LOAD
Name= 1     Rf=1.000  ; G1 Max DB 1선
Lane= L1G1  Class=1  Lmin=   1  Lmax=   1  Sf=2.107
Lane= L1G2  Class=1  Lmin=   1  Lmax=   1  Sf=0.028

Name= 2     Rf=1.000  ; G1 Max DB 2선
Lane= L2G1  Class=1  Lmin=   1  Lmax=   1  Sf=2.897
Lane= L2G1S1  Class=1  Lmin=   1  Lmax=   1  Sf=1.146

Name= 3     Rf=0.900  ; G1 Max DB 3선
Lane= L3G1  Class=1  Lmin=   1  Lmax=   1  Sf=2.867
Lane= L3G1S1  Class=1  Lmin=   1  Lmax=   1  Sf=1.322
Lane= L3G2  Class=1  Lmin=   1  Lmax=   1  Sf=1.811

Name= 4     Rf=1.000  ; G2 Max DB 1선
Lane= L4G1  Class=1  Lmin=   1  Lmax=   1  Sf=0.039
Lane= L4G2  Class=1  Lmin=   1  Lmax=   1  Sf=2.152
```



```
Name= 5     Rf=1.000  ; G2 Max DB 2선
Lane= L5G1  Class=1  Lmin=   1  Lmax=   1  Sf=0.062
Lane= L5G1S1  Class=1  Lmin=   1  Lmax=   1  Sf=1.281
Lane= L5G2  Class=1  Lmin=   1  Lmax=   1  Sf=2.656

Name= 6     Rf=0.900  ; G2 Max DB 3선
Lane= L6G1  Class=1  Lmin=   1  Lmax=   1  Sf=2.090
Lane= L6G1S1  Class=1  Lmin=   1  Lmax=   1  Sf=1.246
Lane= L6G2  Class=1  Lmin=   1  Lmax=   1  Sf=2.664

Name= 7     Rf=1.000  ; G1 Max DL 1선
Lane= L7G1  Class=2  Lmin=   1  Lmax=   1  Sf=3.165
Lane= L7G2  Class=2  Lmin=   1  Lmax=   1  Sf=0.043

Name= 8     Rf=1.000  ; G1 Max DL 2선
Lane= L8G1  Class=2  Lmin=   1  Lmax=   1  Sf=4.342
Lane= L8G1S1  Class=2  Lmin=   1  Lmax=   1  Sf=1.739

Name= 9     Rf=0.900  ; G1 Max DL 3선
Lane= L9G1  Class=2  Lmin=   1  Lmax=   1  Sf=4.310
Lane= L9G1S1  Class=2  Lmin=   1  Lmax=   1  Sf=1.950
Lane= L9G2  Class=2  Lmin=   1  Lmax=   1  Sf=2.740

Name= 10    Rf=1.000  ; G2 Max DL 1선
Lane= L10G1  Class=2  Lmin=   1  Lmax=   1  Sf=0.061
Lane= L10G2  Class=2  Lmin=   1  Lmax=   1  Sf=3.239

Name= 11    Rf=1.000  ; G2 Max DL 2선
Lane= L11G1  Class=2  Lmin=   1  Lmax=   1  Sf=0.063
Lane= L11G1S1  Class=2  Lmin=   1  Lmax=   1  Sf=1.970
Lane= L11G2  Class=2  Lmin=   1  Lmax=   1  Sf=3.967

Name= 12    Rf=0.900  ; G2 Max DL 3선
Lane= L12G1  Class=2  Lmin=   1  Lmax=   1  Sf=3.135
Lane= L12G1S1  Class=2  Lmin=   1  Lmax=   1  Sf=1.877
Lane= L12G2  Class=2  Lmin=   1  Lmax=   1  Sf=3.988

COMBO
Name=G1XDB1  Type=ENVE  ; G1 Max DB 1선
MOVE=1   sf=1.167

Name=G1XDB2  Type=ENVE  ; G1 Max DB 2선
MOVE=2   sf=1.167

Name=G1XDB3  Type=ENVE  ; G1 Max DB 3선
MOVE=3   sf=1.167

Name=G2XDB1  Type=ENVE  ; G2 Max DB 1선
MOVE=4   sf=1.167

Name=G2XDB2  Type=ENVE  ; G2 Max DB 2선
MOVE=5   sf=1.167

Name=G2XDB3  Type=ENVE  ; G2 Max DB 3선
MOVE=6   sf=1.167

Name=G1XDL1  Type=ENVE  ; G1 Max DL 1선
MOVE=7   sf=1.167

Name=G1XDL2  Type=ENVE  ; G1 Max DL 2선
MOVE=8   sf=1.167

Name=G1XDL3  Type=ENVE  ; G1 Max DL 3선
MOVE=9   sf=1.167

Name=G2XDL1  Type=ENVE  ; G2 Max DL 1선
MOVE=10   sf=1.167

Name=G2XDL2  Type=ENVE  ; G2 Max DL 2선
MOVE=11   sf=1.167

Name=G2XDL3  Type=ENVE  ; G2 Max DL 3선
MOVE=12   sf=1.167
```



```
Name=DB  Type=ENVE  ;
COMB=G1XDB1   sf=1.000
COMB=G1XDB2   sf=1.000
COMB=G1XDB3   sf=1.000
COMB=G2XDB1   sf=1.000
COMB=G2XDB2   sf=1.000
COMB=G2XDB3   sf=1.000

Name=DL  Type=ENVE  ;
COMB=G1XDL1   sf=1.000
COMB=G1XDL2   sf=1.000
COMB=G1XDL3   sf=1.000
COMB=G2XDL1   sf=1.000
COMB=G2XDL2   sf=1.000
COMB=G2XDL3   sf=1.000

Name=CAR  Type=ENVE  ;
COMB=DB   sf=1.000
COMB=DL   sf=1.000

Name=DESIGN  Type=ENVE  ;
COMB=CAR   sf=1.000

OUTPUT
ELEM=JOINT    TYPE=DISP,REAC      LOAD=*   COMB=*
ELEM=FRAME    TYPE=FORCE          LOAD=*   COMB=*
```


4) 부등침하

```
< UNEQUAL SETTLEMENT >

SYSTEM
LENGTH=M                FORCE=KN

JOINT
1  X= 0.000    Y=0.000    Z=0.000
2  X= 4.450    Y=0.000    Z=0.000
3  X= 9.450    Y=0.000    Z=0.000
4  X= 14.450   Y=0.000    Z=0.000
5  X= 19.450   Y=0.000    Z=0.000
6  X= 24.450   Y=0.000    Z=0.000
7  X= 29.450   Y=0.000    Z=0.000
8  X= 34.450   Y=0.000    Z=0.000
9  X= 39.450   Y=0.000    Z=0.000
10  X= 44.450   Y=0.000   Z=0.000
11  X= 49.450   Y=0.000   Z=0.000
12  X= 54.450   Y=0.000   Z=0.000
13  X= 59.450   Y=0.000   Z=0.000
14  X= 64.450   Y=0.000   Z=0.000
15  X= 69.450   Y=0.000   Z=0.000
16  X= 74.450   Y=0.000   Z=0.000
17  X= 79.450   Y=0.000   Z=0.000
18  X= 84.450   Y=0.000   Z=0.000
19  X= 89.450   Y=0.000   Z=0.000
20  X= 94.450   Y=0.000   Z=0.000
21  X= 99.450   Y=0.000   Z=0.000
22  X= 104.030   Y=0.000   Z=0.000
23  X= 0.000   Y=-7.700   Z=-0.154
24  X= 4.450   Y=-7.700   Z=-0.154
25  X= 9.450   Y=-7.700   Z=-0.154
26  X= 14.450   Y=-7.700   Z=-0.154
27  X= 19.450   Y=-7.700   Z=-0.154
28  X= 24.450   Y=-7.700   Z=-0.154
29  X= 29.450   Y=-7.700   Z=-0.154
30  X= 34.450   Y=-7.700   Z=-0.154
31  X= 39.450   Y=-7.700   Z=-0.154
32  X= 44.450   Y=-7.700   Z=-0.154
33  X= 49.450   Y=-7.700   Z=-0.154
34  X= 54.450   Y=-7.700   Z=-0.154
35  X= 59.450   Y=-7.700   Z=-0.154
36  X= 64.450   Y=-7.700   Z=-0.154
37  X= 69.450   Y=-7.700   Z=-0.154
38  X= 74.450   Y=-7.700   Z=-0.154
39  X= 79.450   Y=-7.700   Z=-0.154
40  X= 84.450   Y=-7.700   Z=-0.154
41  X= 89.450   Y=-7.700   Z=-0.154
42  X= 94.450   Y=-7.700   Z=-0.154
43  X= 99.450   Y=-7.700   Z=-0.154
44  X= 104.030   Y=-7.700   Z=-0.154
45  X= 0.000   Y=-3.850   Z=-0.077
46  X= 4.450   Y=-3.850   Z=-0.077
47  X= 9.450   Y=-3.850   Z=-0.077
48  X= 14.450   Y=-3.850   Z=-0.077
49  X= 19.450   Y=-3.850   Z=-0.077
50  X= 24.450   Y=-3.850   Z=-0.077
51  X= 29.450   Y=-3.850   Z=-0.077
52  X= 34.450   Y=-3.850   Z=-0.077
53  X= 39.450   Y=-3.850   Z=-0.077
54  X= 44.450   Y=-3.850   Z=-0.077
55  X= 49.450   Y=-3.850   Z=-0.077
56  X= 54.450   Y=-3.850   Z=-0.077
57  X= 59.450   Y=-3.850   Z=-0.077
58  X= 64.450   Y=-3.850   Z=-0.077
59  X= 69.450   Y=-3.850   Z=-0.077
60  X= 74.450   Y=-3.850   Z=-0.077
61  X= 79.450   Y=-3.850   Z=-0.077
62  X= 84.450   Y=-3.850   Z=-0.077
63  X= 89.450   Y=-3.850   Z=-0.077
64  X= 94.450   Y=-3.850   Z=-0.077
65  X= 99.450   Y=-3.850   Z=-0.077
```

```
66  X= 104.030    Y=-3.850    Z=-0.077
67  X= 0.000     Y=0.000     Z=-1.150
68  X= 0.000     Y=1.050     Z=-1.150
69  X= 0.000     Y=-1.050    Z=-1.150
70  X= 54.450    Y=0.000     Z=-1.250
71  X= 54.450    Y=1.050     Z=-1.250
72  X= 54.450    Y=-1.050    Z=-1.250
73  X= 104.030   Y=0.000     Z=-1.150
74  X= 104.030   Y=1.050     Z=-1.150
75  X= 104.030   Y=-1.050    Z=-1.150
76  X= 0.000     Y=-7.700    Z=-1.304
77  X= 0.000     Y=-6.650    Z=-1.304
78  X= 0.000     Y=-8.750    Z=-1.304
79  X= 54.450    Y=-7.700    Z=-1.404
80  X= 54.450    Y=-6.650    Z=-1.404
81  X= 54.450    Y=-8.750    Z=-1.404
82  X= 104.030   Y=-7.700    Z=-1.304
83  X= 104.030   Y=-6.650    Z=-1.304
84  X= 104.030   Y=-8.750    Z=-1.304

LOCAL
ADD=  68  ANG=0.000
ADD=  69  ANG=0.000
ADD=  71  ANG=0.000
ADD=  72  ANG=0.000
ADD=  74  ANG=0.000
ADD=  75  ANG=0.000
ADD=  77  ANG=5.872
ADD=  78  ANG=8.049
ADD=  80  ANG=0.000
ADD=  81  ANG=0.000
ADD=  83  ANG=-6.444
ADD=  84  ANG=-8.828

RESTRAINT
ADD=  68  DOF=       U2, U3,
ADD=  69  DOF=       U2, U3,
ADD=  71  DOF= U1, U2, U3,
ADD=  72  DOF= U1, U2, U3,
ADD=  74  DOF=       U2, U3,
ADD=  75  DOF=       U2, U3,
ADD=  77  DOF=           U3,
ADD=  78  DOF=           U3,
ADD=  80  DOF= U1,       U3,
ADD=  81  DOF= U1,       U3,
ADD=  83  DOF=           U3,
ADD=  84  DOF=           U3,

MATERIAL
Name=1
E=2.05e+008
Name=2
E=2.05e+008
Name=3
E=2.05e+008
Name=4
E=2.05e+008
Name=5
E=2.05e+008
Name=6
E=2.05e+008
Name=7
E=2.05e+008
Name=8
E=2.05e+008
Name=9
E=2.05e+008
Name=10
E=2.05e+008
Name=11
E=2.05e+008
Name=12
E=2.05e+008
```



```
Name=13
E=2.05e+008
Name=14
E=2.05e+008
Name=15
E=2.05e+008
Name=16
E=2.05e+008
Name=17
E=2.05e+008
Name=18
E=2.05e+008
Name=19
E=2.05e+008
Name=20
E=2.05e+008
Name=21
E=2.05e+008

FRAME SECTION
Name=   1  Mat=   1  A=0.31086  I=0.23700884, 0.81280104  J=0.19666515   ; GIRDER
Name=   2  Mat=   2  A=0.31486  I=0.28250528, 0.82062503  J=0.22101250   ; GIRDER
Name=   3  Mat=   3  A=0.32662  I=0.33306917, 0.83043848  J=0.24351348   ; GIRDER
Name=   4  Mat=   4  A=0.36190  I=0.40869340, 0.85935523  J=0.26781294   ; GIRDER
Name=   5  Mat=   5  A=0.37282  I=0.44508691, 0.86633164  J=0.26781294   ; GIRDER
Name=   6  Mat=   6  A=0.34706  I=0.39688457, 0.84641193  J=0.25410445   ; GIRDER
Name=   7  Mat=   7  A=0.45526  I=0.58100343, 0.95508413  J=0.38096295   ; GIRDER
Name=   8  Mat=   8  A=0.35014  I=0.38385500, 0.85582068  J=0.26087422   ; GIRDER
Name=   9  Mat=   9  A=0.33838  I=0.38030356, 0.84015859  J=0.25819292   ; GIRDER
Name=  10  Mat=  10  A=0.30466  I=0.23540042, 0.75928243  J=0.19666515   ; GIRDER
Name=  11  Mat=  11  A=0.30866  I=0.28057184, 0.76728296  J=0.22101250   ; GIRDER
Name=  12  Mat=  12  A=0.32042  I=0.33057213, 0.77758860  J=0.24351348   ; GIRDER
Name=  13  Mat=  13  A=0.35570  I=0.40556776, 0.80777754  J=0.26781294   ; GIRDER
Name=  14  Mat=  14  A=0.36662  I=0.44146450, 0.81509583  J=0.26781294   ; GIRDER
Name=  15  Mat=  15  A=0.34086  I=0.39364487, 0.79433278  J=0.25410445   ; GIRDER
Name=  16  Mat=  16  A=0.44906  I=0.57632641, 0.90587243  J=0.38096295   ; GIRDER
Name=  17  Mat=  17  A=0.34394  I=0.38093229, 0.80384935  J=0.26087422   ; GIRDER
Name=  18  Mat=  18  A=0.33218  I=0.37721604, 0.78776432  J=0.25819292   ; GIRDER
Name=  19  Mat=  19  A=0.02880  I=0.01174211, 0.00005426  J=0.00000138   ; CROSSBEAM
Name=  20  Mat=  20  A=0.01680  I=0.00169891, 0.00005412  J=0.00000081   ; STRINGER
Name=  21  Mat=  21  A=10.00000  I=10.00000000, 10.00000000  J=10.00000000    ; SHOE
Name=  22  Type=Nonpr  Sec=   1,   2  Elvar=2,1
Name=  23  Type=Nonpr  Sec=   2,   1
Name=  24  Type=Nonpr  Sec=   2,   3
Name=  25  Type=Nonpr  Sec=   3,   4
Name=  26  Type=Nonpr  Sec=   4,   5
Name=  27  Type=Nonpr  Sec=   5,   6
Name=  28  Type=Nonpr  Sec=   6,   7
Name=  29  Type=Nonpr  Sec=   6,   8
Name=  30  Type=Nonpr  Sec=   7,   6
Name=  31  Type=Nonpr  Sec=   8,   9
Name=  32  Type=Nonpr  Sec=   9,   2
Name=  33  Type=Nonpr  Sec=  10,  11
Name=  34  Type=Nonpr  Sec=  11,  10
Name=  35  Type=Nonpr  Sec=  11,  12
Name=  36  Type=Nonpr  Sec=  12,  13
Name=  37  Type=Nonpr  Sec=  13,  14
Name=  38  Type=Nonpr  Sec=  14,  15
Name=  39  Type=Nonpr  Sec=  15,  16
Name=  40  Type=Nonpr  Sec=  15,  17
Name=  41  Type=Nonpr  Sec=  16,  15
Name=  42  Type=Nonpr  Sec=  17,  18
Name=  43  Type=Nonpr  Sec=  18,  11

FRAME
1  J=  1,   2  Sec=22  Local=12  Pldir=+Z,+X  NSEG=4
2  J=  2,   3  Sec=24
3  J=  3,   4  Sec=25
4  J=  4,   5  Sec= 4
5  J=  5,   6  Sec= 4
6  J=  6,   7  Sec= 4
7  J=  7,   8  Sec= 4
8  J=  8,   9  Sec=26
```



```
9  J=  9,  10  Sec=27
10  J= 10,  11  Sec=28
11  J= 11,  12  Sec= 7
12  J= 12,  13  Sec= 7
13  J= 13,  14  Sec=30
14  J= 14,  15  Sec=29
15  J= 15,  16  Sec= 8
16  J= 16,  17  Sec= 8
17  J= 17,  18  Sec= 8
18  J= 18,  19  Sec= 8
19  J= 19,  20  Sec=31
20  J= 20,  21  Sec=32
21  J= 21,  22  Sec=23
22  J= 23,  24  Sec=33
23  J= 24,  25  Sec=35
24  J= 25,  26  Sec=36
25  J= 26,  27  Sec=13
26  J= 27,  28  Sec=13
27  J= 28,  29  Sec=13
28  J= 29,  30  Sec=13
29  J= 30,  31  Sec=37
30  J= 31,  32  Sec=38
31  J= 32,  33  Sec=39
32  J= 33,  34  Sec=16
33  J= 34,  35  Sec=16
34  J= 35,  36  Sec=41
35  J= 36,  37  Sec=40
36  J= 37,  38  Sec=17
37  J= 38,  39  Sec=17
38  J= 39,  40  Sec=17
39  J= 40,  41  Sec=17
40  J= 41,  42  Sec=42
41  J= 42,  43  Sec=43
42  J= 43,  44  Sec=34
43  J=  1,  45  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
44  J= 45,  23  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
45  J=  2,  46  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
46  J= 46,  24  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
47  J=  3,  47  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
48  J= 47,  25  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
49  J=  4,  48  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
50  J= 48,  26  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
51  J=  5,  49  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
52  J= 49,  27  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
53  J=  6,  50  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
54  J= 50,  28  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
55  J=  7,  51  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
56  J= 51,  29  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
57  J=  8,  52  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
58  J= 52,  30  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
59  J=  9,  53  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
60  J= 53,  31  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
61  J= 10,  54  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
62  J= 54,  32  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
63  J= 11,  55  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
64  J= 55,  33  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
65  J= 12,  56  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
66  J= 56,  34  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
67  J= 13,  57  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
68  J= 57,  35  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
69  J= 14,  58  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
70  J= 58,  36  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
71  J= 15,  59  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
72  J= 59,  37  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
73  J= 16,  60  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
74  J= 60,  38  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
75  J= 17,  61  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
76  J= 61,  39  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
77  J= 18,  62  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
78  J= 62,  40  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
79  J= 19,  63  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
80  J= 63,  41  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
81  J= 20,  64  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
```



```
82  J= 64,  42  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
83  J= 21,  65  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
84  J= 65,  43  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
85  J= 22,  66  Sec=19  IOFF=1.350  JOFF=0.000  RIGID=1.0
86  J= 66,  44  Sec=19  IOFF=0.000  JOFF=1.350  RIGID=1.0
87  J= 45,  46  Sec=20
88  J= 46,  47  Sec=20
89  J= 47,  48  Sec=20
90  J= 48,  49  Sec=20
91  J= 49,  50  Sec=20
92  J= 50,  51  Sec=20
93  J= 51,  52  Sec=20
94  J= 52,  53  Sec=20
95  J= 53,  54  Sec=20
96  J= 54,  55  Sec=20
97  J= 55,  56  Sec=20
98  J= 56,  57  Sec=20
99  J= 57,  58  Sec=20
100  J= 58,  59  Sec=20
101  J= 59,  60  Sec=20
102  J= 60,  61  Sec=20
103  J= 61,  62  Sec=20
104  J= 62,  63  Sec=20
105  J= 63,  64  Sec=20
106  J= 64,  65  Sec=20
107  J= 65,  66  Sec=20
108  J=  1,  67  Sec=21
109  J= 68,  67  Sec=21
110  J= 69,  67  Sec=21
111  J= 12,  70  Sec=21
112  J= 71,  70  Sec=21
113  J= 72,  70  Sec=21
114  J= 22,  73  Sec=21
115  J= 74,  73  Sec=21
116  J= 75,  73  Sec=21
117  J= 23,  76  Sec=21
118  J= 77,  76  Sec=21
119  J= 78,  76  Sec=21
120  J= 34,  79  Sec=21
121  J= 80,  79  Sec=21
122  J= 81,  79  Sec=21
123  J= 44,  82  Sec=21
124  J= 83,  82  Sec=21
125  J= 84,  82  Sec=21

LOAD
Name=A1  :  UNEQUAL SETTLEMENT
Type=RESTRAINT  DISPLACEMENT
Add= 68      Uz=-0.010
Add= 69      Uz=-0.010
Add= 77      Uz=-0.010
Add= 78      Uz=-0.010

Name=P1  :  UNEQUAL SETTLEMENT
Type=RESTRAINT  DISPLACEMENT
Add= 71      Uz=-0.010
Add= 72      Uz=-0.010
Add= 80      Uz=-0.010
Add= 81      Uz=-0.010

Name=A2  :  UNEQUAL SETTLEMENT
Type=RESTRAINT  DISPLACEMENT
Add= 74      Uz=-0.010
Add= 75      Uz=-0.010
Add= 83      Uz=-0.010
Add= 84      Uz=-0.010

COMBO
Name=2N1  Type=ENVE  :
LOAD=A1   sf=1.000
LOAD=P1   sf=1.000

Name=2N2  Type=ENVE  :
```

```
LOAD=A1    sf=1.000
LOAD=A2    sf=1.000

Name=2N3   Type=ENVE   :
LOAD=P1    sf=1.000
LOAD=A2    sf=1.000

Name=2N   Type=ENVE   :
COMB=2N1    sf=1.000
COMB=2N2    sf=1.000
COMB=2N3    sf=1.000

Name=SETTLE   Type=ENVE   :
LOAD=A1    sf=1.000
LOAD=P1    sf=1.000
LOAD=A2    sf=1.000
COMB=2N    sf=1.000

OUTPUT
ELEM=JOINT     TYPE=DISP,REAC          LOAD=*    COMB=*
ELEM=FRAME     TYPE=FORCE              LOAD=*    COMB=*
```